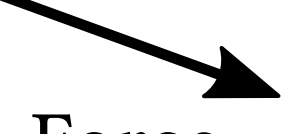
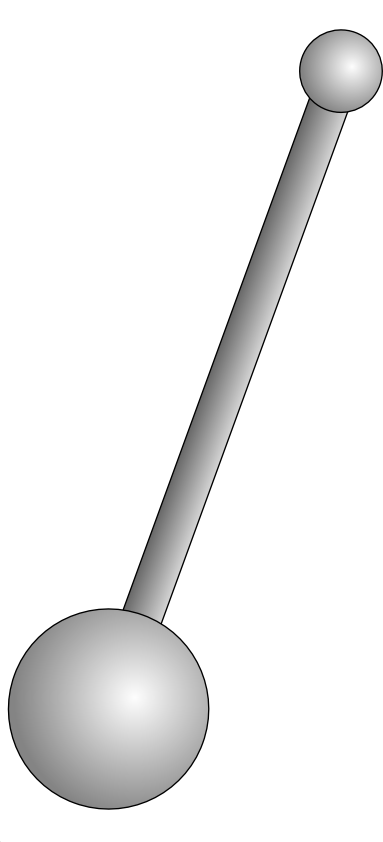
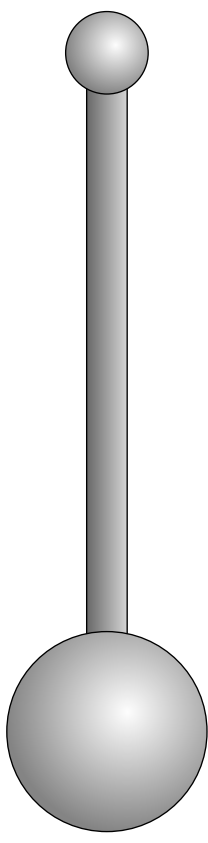


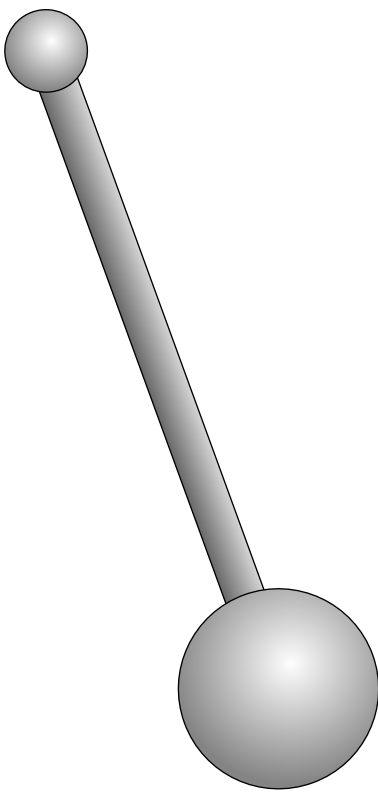
Equilibrium position



Force



Inertia



Force